

**SIGGRAPH 2021**

## **REVISITING INTEGRATION IN THE MATERIAL POINT METHOD**

**A SCHEME FOR EASIER SEPARATION AND LESS DISSIPATION**

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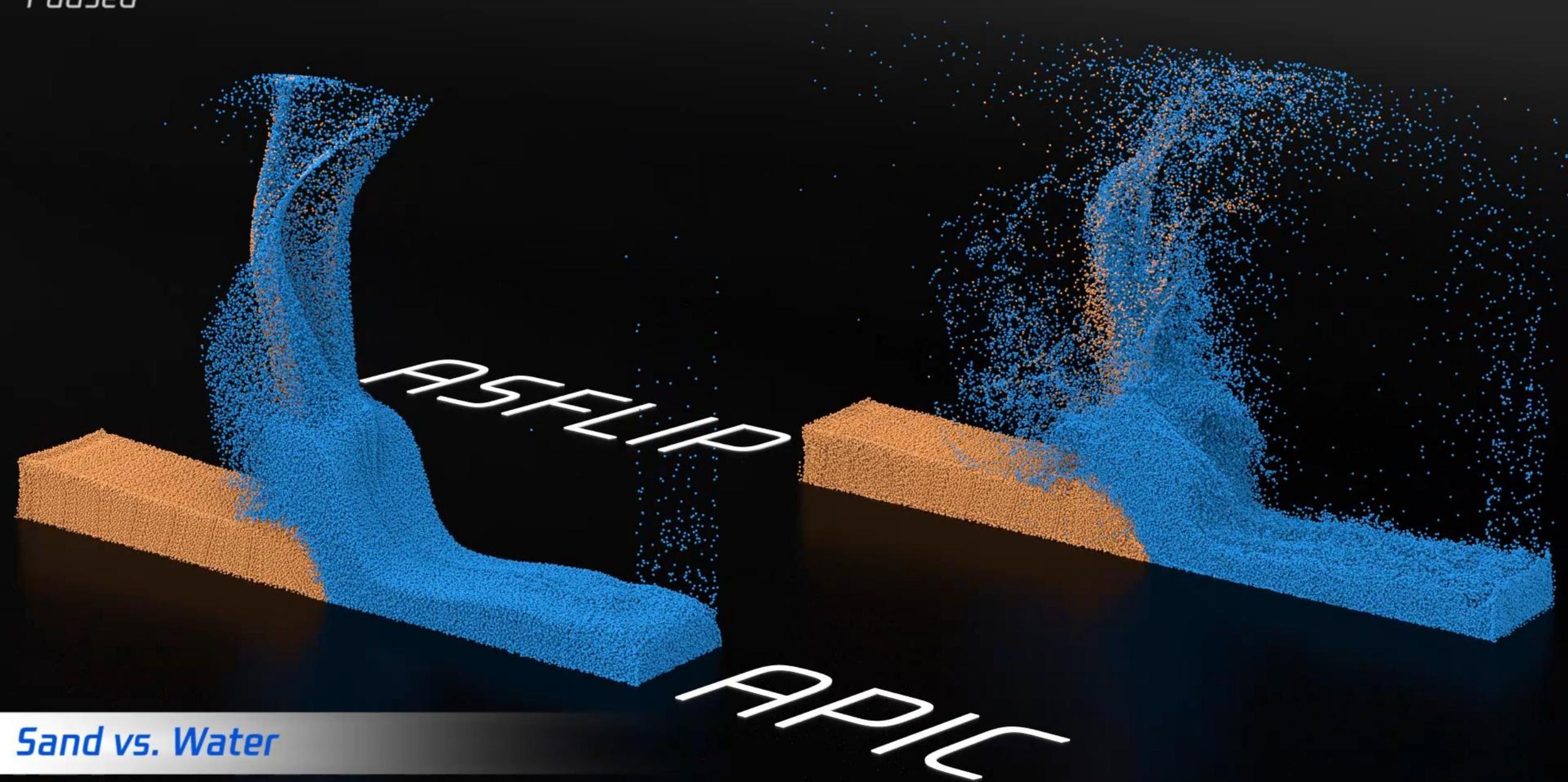
TENCENT GAME AI RESEARCH CENTER

**CROS**

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THE PREMIER CONFERENCE & EXHIBITION IN  
COMPUTER GRAPHICS & INTERACTIVE TECHNIQUES

Paused



Sand vs. Water



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# *MOTIVATION*

*WHY WE NEED A NEW INTEGRATION SCHEME?*



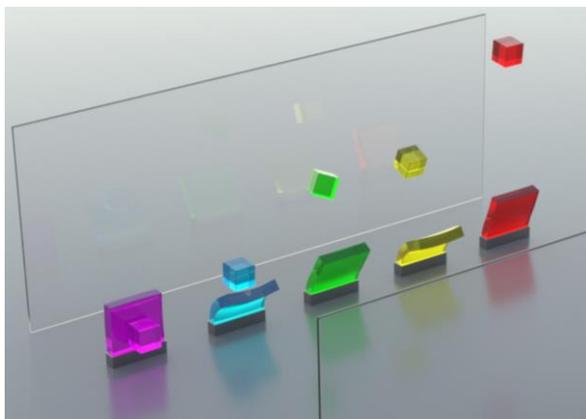


## A CASE IN PRODUCTION

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- 93,014 strands
- 7,179,350 DoFs
- Required simulation cost
  - ~ 6s per frame (based on 60 frame per simulated second)
  - ~ 1h in total (10s simulation)

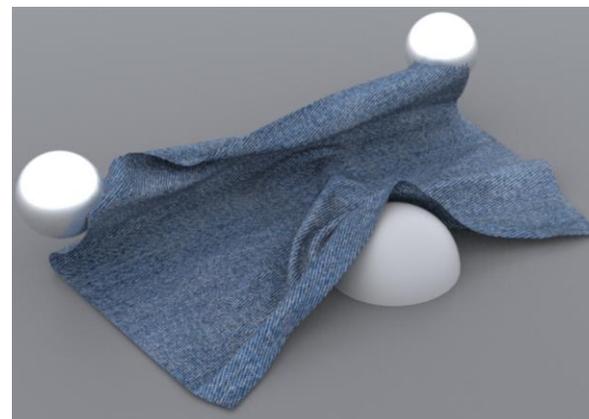
### Simulate with GPU-MPM?



*[Jiang et al. 2015]*



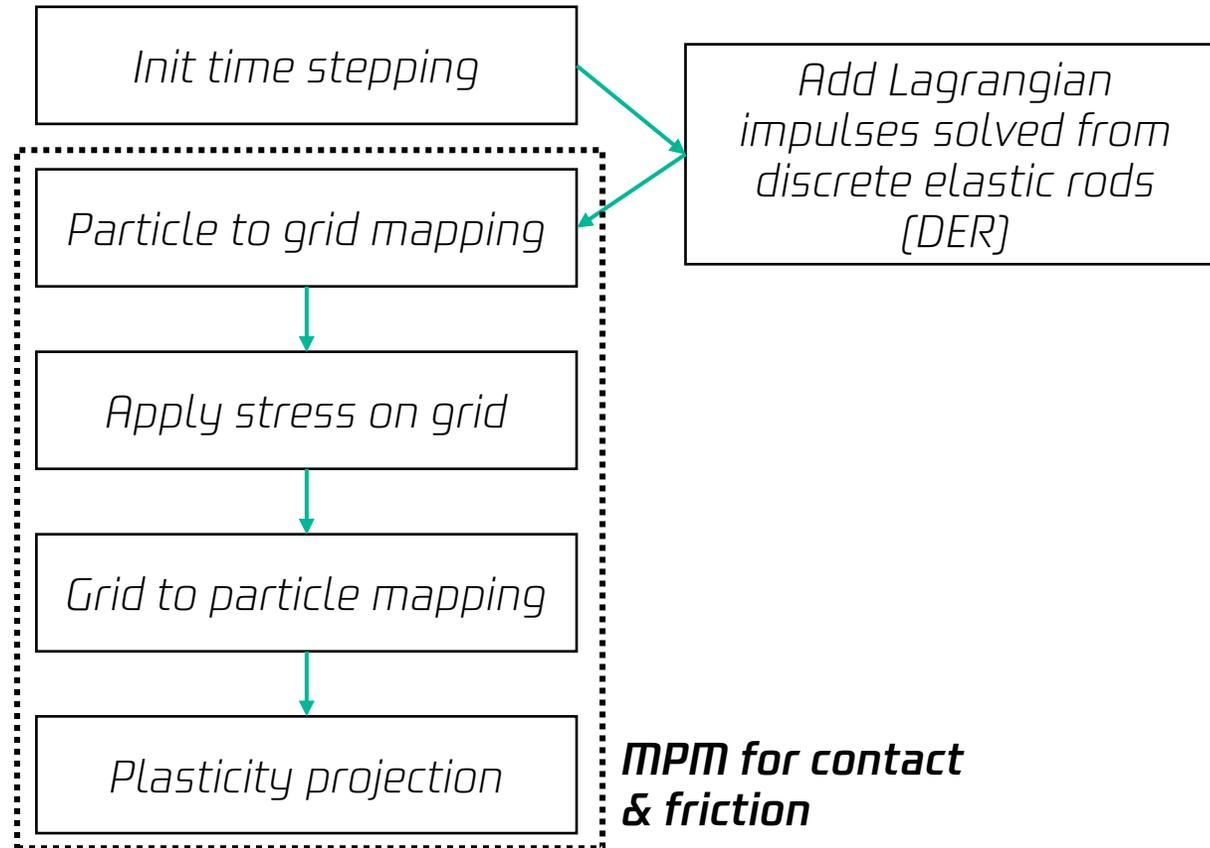
*[Jiang et al. 2017]*



*[Guo et al. 2018]*



*[Han et al. 2019]*



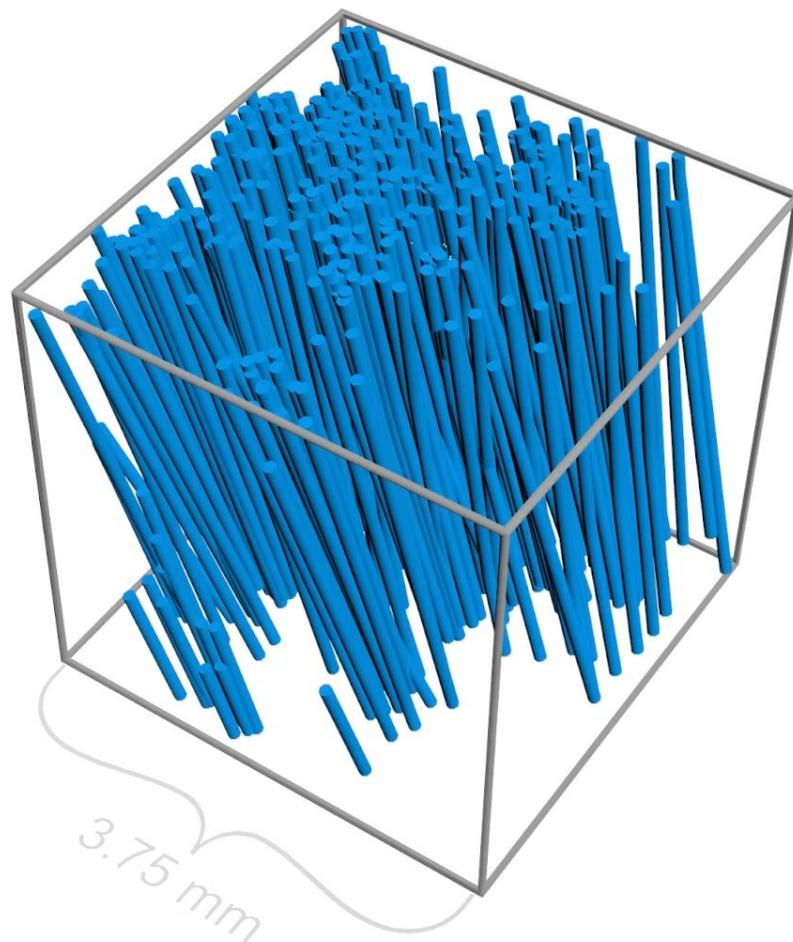
## Our MPM Hair Simulator

→ **HAIRS SIMULATED WITH MLS-MPM + FLIP**

**NEXT**  
STUDIOS



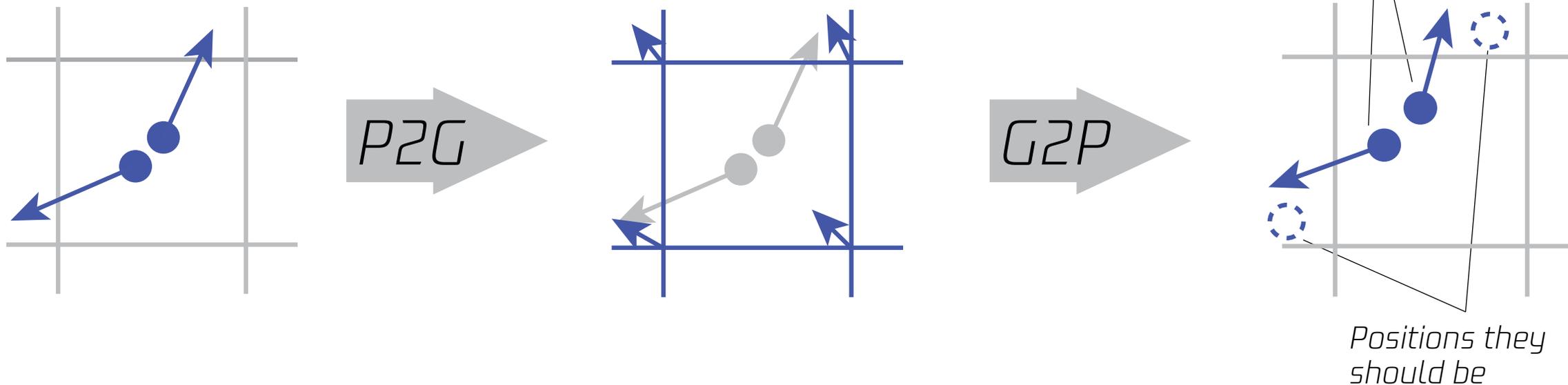
# → HAIRS SIMULATED WITH MLS-MPM + FLIP



**Position update** during grid-to-particle (G2P) transfer:

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

Interpolated from current nodal velocity



*PIC grid-to-particle:*  
[Harlow et al. 1955]

*APIC grid-to-particle:*  
[moving-least-square version]  
[Jiang et al. 2015, Hu et al. 2018]

*PolyPIC grid-to-particle:*  
[Fu et al. 2017]

Velocity  
Update

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{C}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* (\mathbf{x}_i^n - \mathbf{x}_p^n)^T (\mathbf{D}_p^n)^{-1}$$

$$\mathbf{C}_p^{n+1} = \underset{c}{\operatorname{argmin}} \sum_i m_{ip}^n \left| \mathbf{v}_i^* - \sum_r \sum_\alpha s_r (\mathbf{x}_i - \mathbf{x}_p^n) e_\alpha c_{pr\alpha}^{n+1} \right|^2$$

Position  
Update

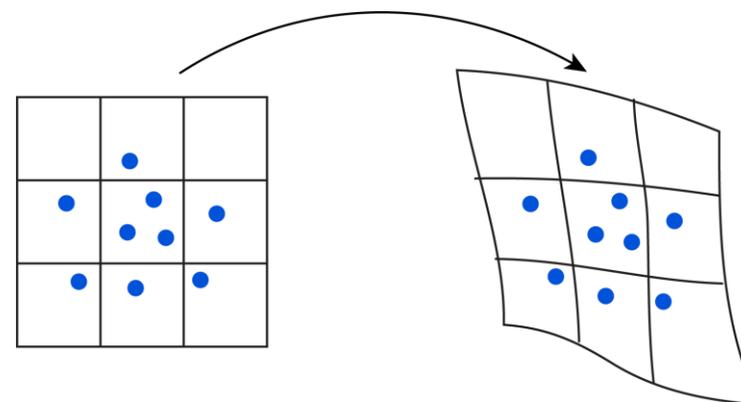
$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

- FLIP/xPIC assumes material **continuous in the entire domain**.
- Problem:
  - Particle position is **always** interpolated from deformed nodal positions
  - If any movement is **not capturable** by grid, it would be **neither capturable** by particles.

Continuous deformation  $\Psi$

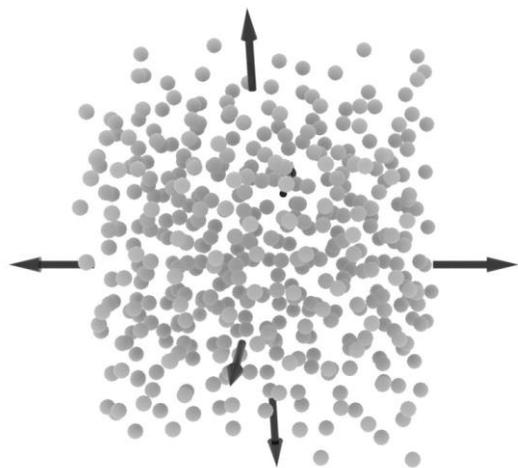


$$\frac{\partial \mathbf{x}}{\partial t} = \frac{\partial \Psi(\mathbf{X}, t)}{\partial t} \approx \sum_i w_{ip} \mathbf{v}_i^*$$

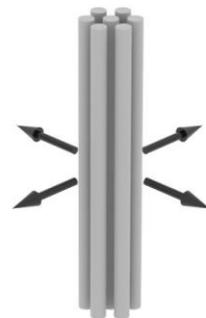
$$\mathbf{x}_p^{n+1} = \sum_i w_{ip} \mathbf{x}_i^*$$

# → DISCREPANCY

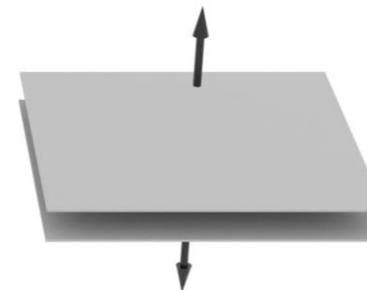
BETWEEN RENDERING, EXPECTATION AND SIMULATION



*Sand*



*Hairs*



*Clothes*

Expected behavior: **separate immediately** when pulled apart

Rendering: **discrete & separated** elements

Simulation: **continuum** that trap particles until they have no shared weights on a node



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***nFLIP***

***NATURALLY-MODIFIED FLIP***



*FLIP* grid-to-particle:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right)$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

*Assume material continuous everywhere.*

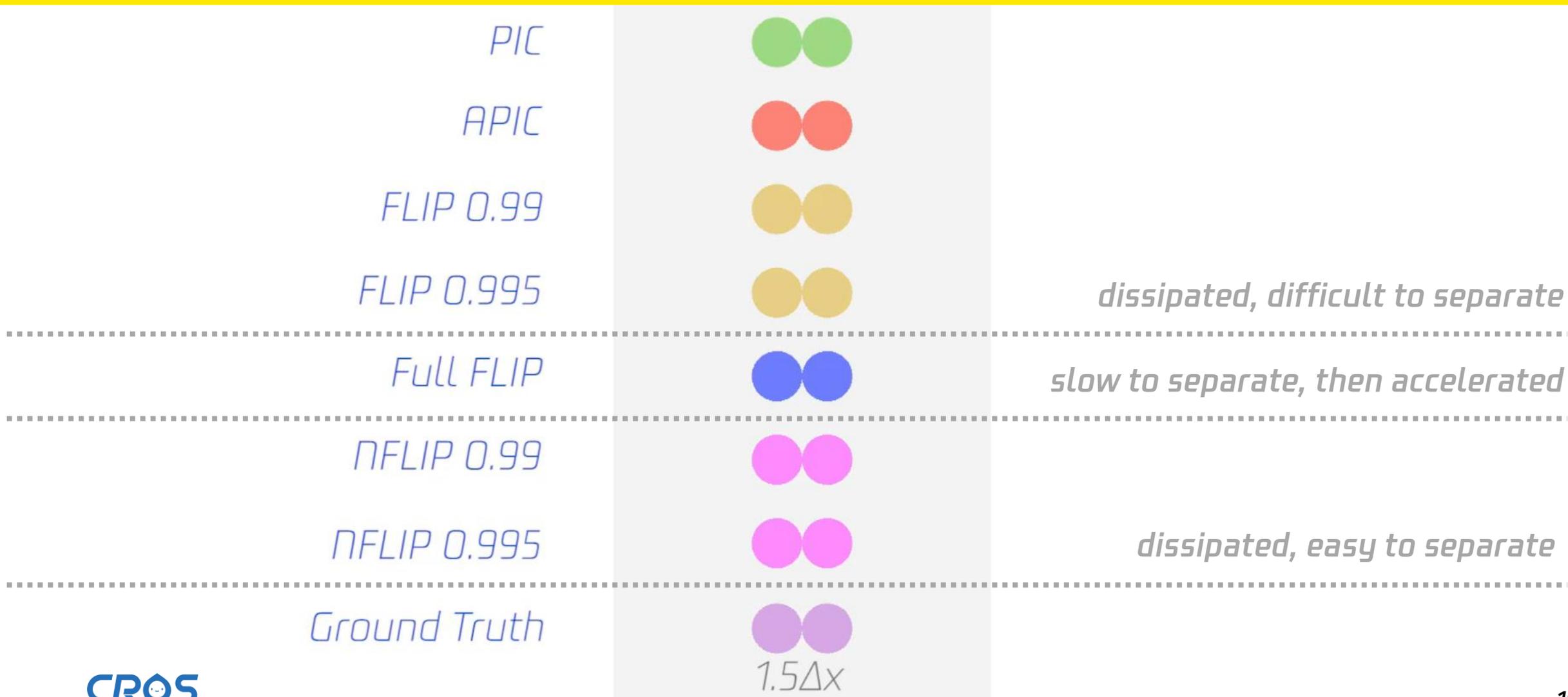
*NFLIP* grid-to-particle:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right)$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \mathbf{v}_p^{n+1}$$

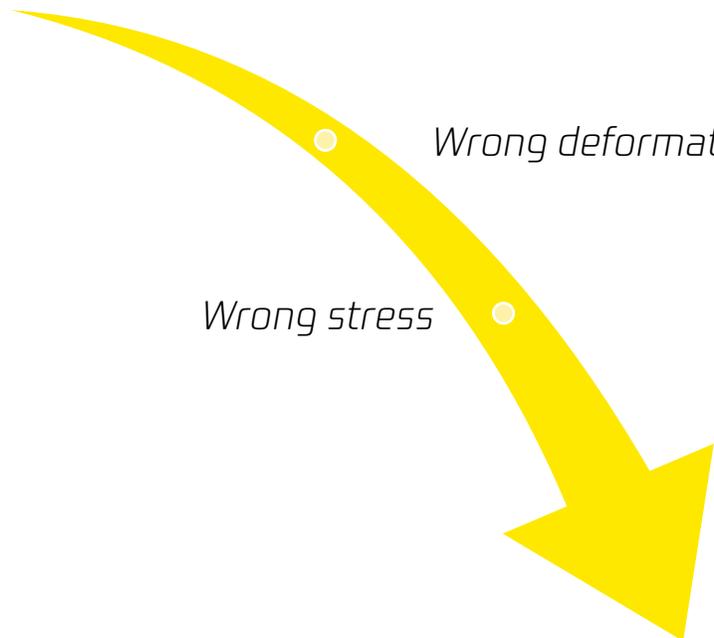
*Completely ignore continuity.*

# → NFLIP: USE PARTICLE VELOCITY FOR ADVECTION



# → IGNORING CONTINUITY LEADS TO ERROR

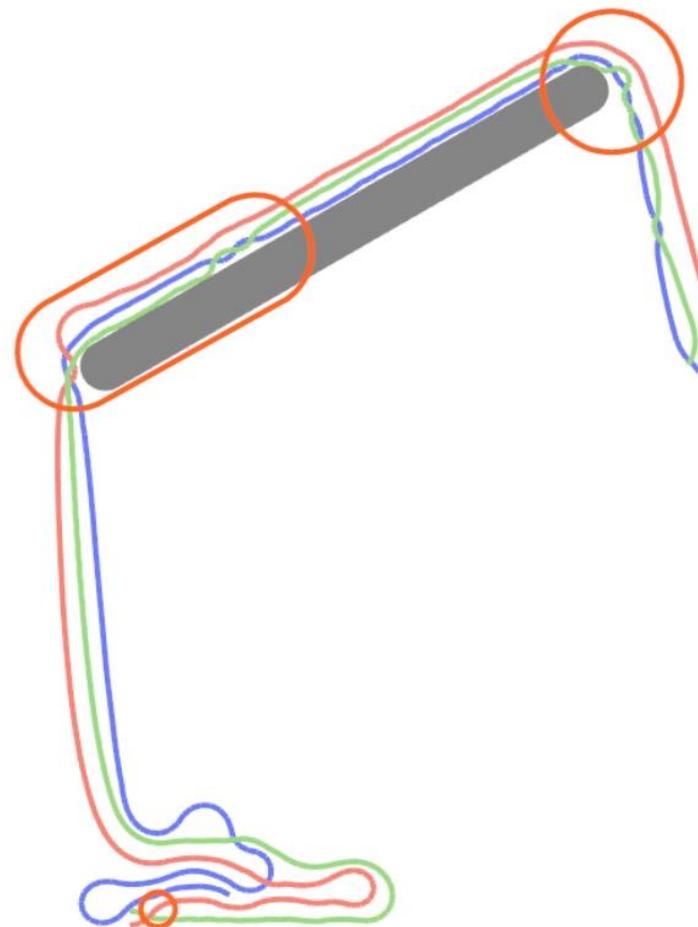
*Ignoring continuity*



*Wrong deformation gradient*

*Wrong stress*

*Wrong contacts and frictions*





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***SFLIP***

***A SEPARABLE FLIP***



FLIP grid-to-particle:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right)$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

SFLIP grid-to-particle:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right)$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \left[ \sum_i w_{ip} \mathbf{v}_i^* + \beta_p \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \right]$$

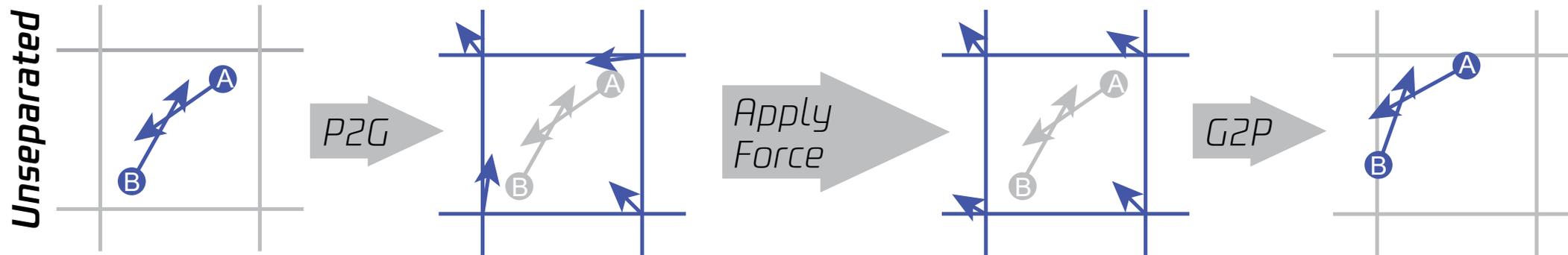
$\beta_p$ : the trap-breaking ratio

FLIP:  $\forall p, \beta_p = 0$

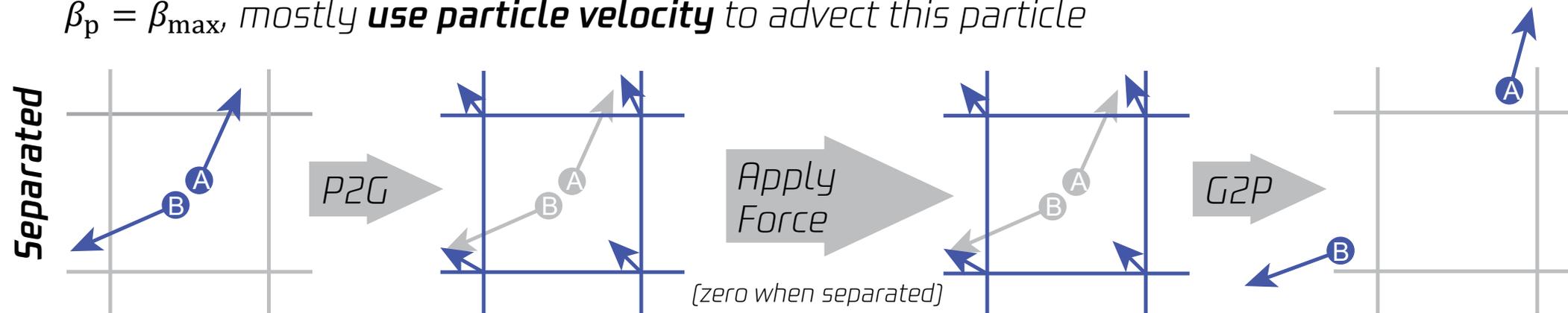
$\Pi$ FLIP:  $\forall p, \beta_p = 1$

# → THE TRAP-BREAKING RATIO $\beta_p$

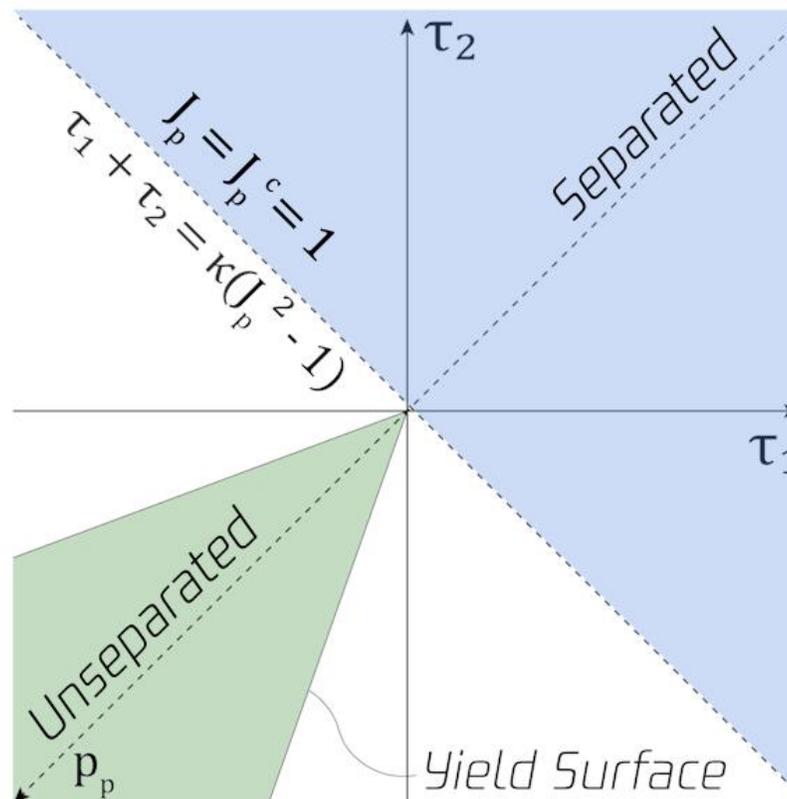
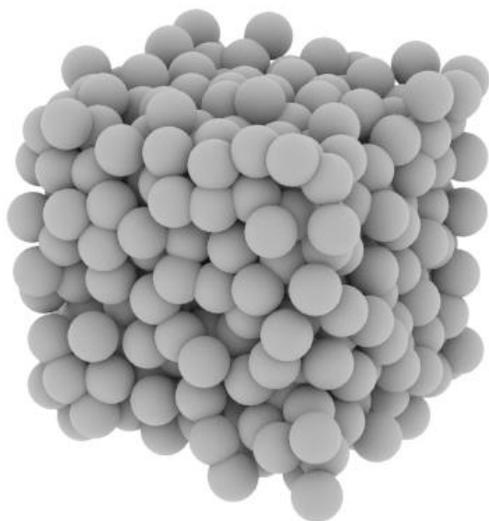
$\beta_p = \beta_{\min}$ , mostly use interpolated nodal velocity to advect this particle



$\beta_p = \beta_{\max}$ , mostly **use particle velocity** to advect this particle

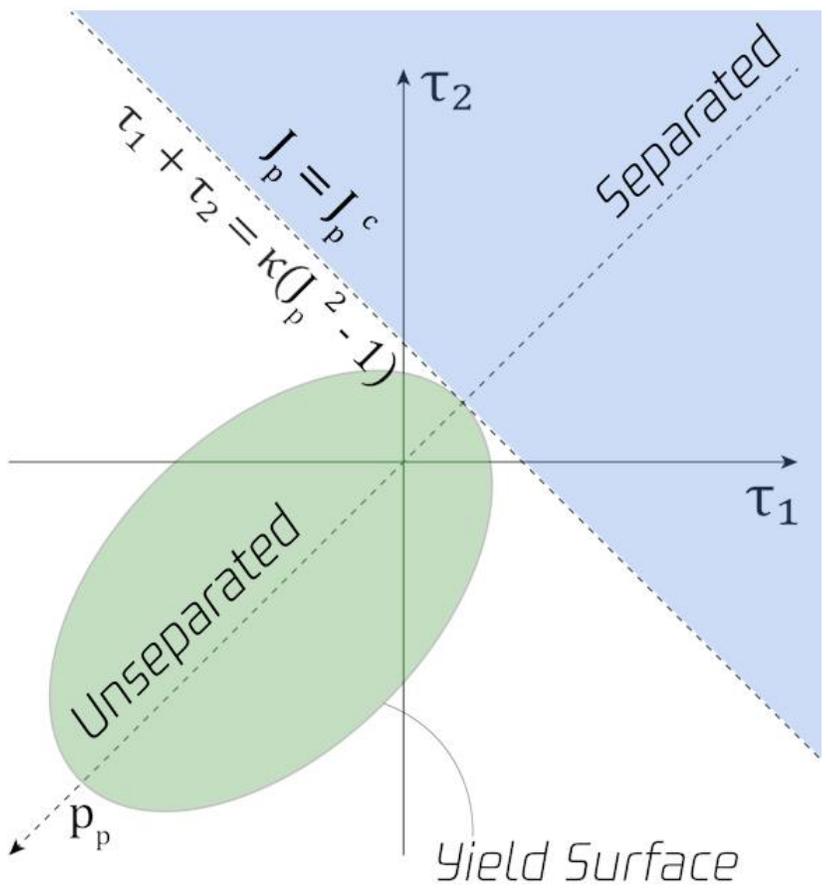
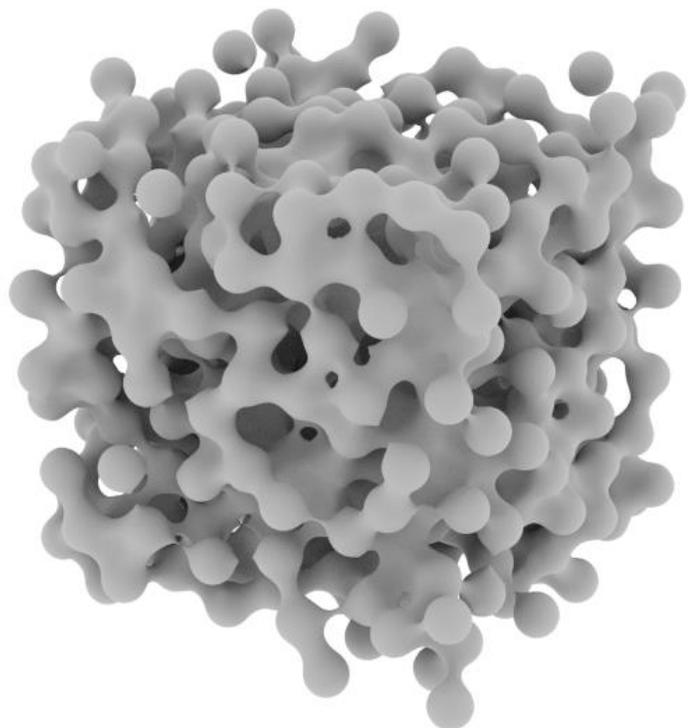


# → DETERMINE SEPARATION THROUGH VOLUME RATIO



$\tau_1, \tau_2$ : stress  
 $J_p$ : volume ratio  
 $p_p$ : pressure  
 $\kappa$ : bulk modulus  
 $J_p^c$ : critical volume ratio

# → DETERMINE SEPARATION THROUGH VOLUME RATIO



$\tau_1, \tau_2$ : stress  
 $J_p$ : volume ratio  
 $p_p$ : pressure  
 $\kappa$ : bulk modulus  
 $J_p^c$ : critical volume ratio

SFLIP grid-to-particle:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right)$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \left[ \sum_i w_{ip} \mathbf{v}_i^* + \beta_p \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \right]$$

$$\beta_p = \begin{cases} 0, & \text{in boundary} \\ \beta_{\min}, & J_p < J_p^c \\ \beta_{\max}, & J_p \geq J_p^c \end{cases}$$



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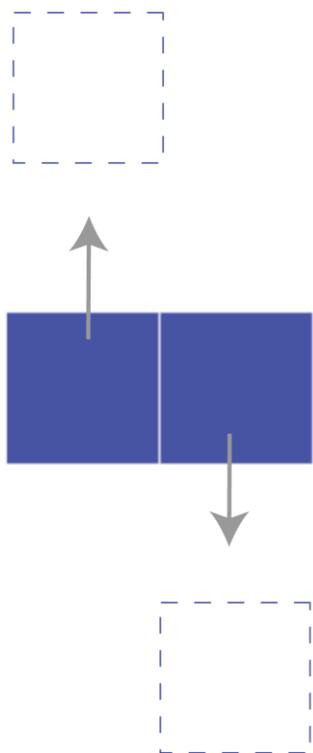
***SFLIP***

*DIDACTIC EXAMPLES*

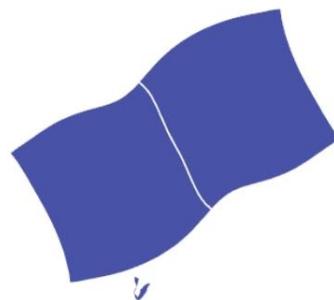


# → TWO PERFECTLY SMOOTH FINITE ELEMENT SQUARES NO FORCE APPLIED FROM ONE SQUARE TO ANOTHER

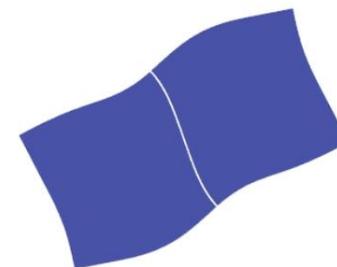
Ground Truth



FLIP



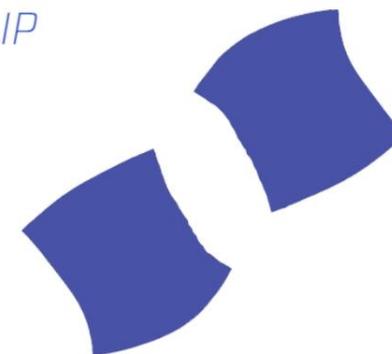
APIC



nFLIP



SFLIP





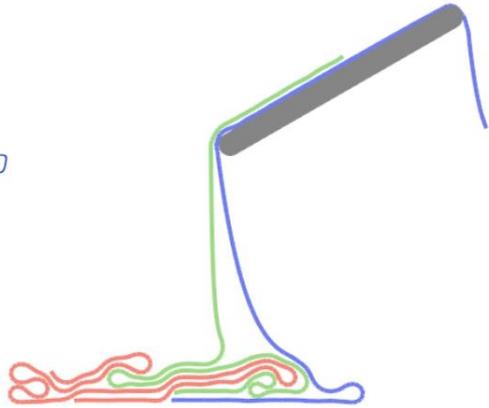
# 2D FIBERS



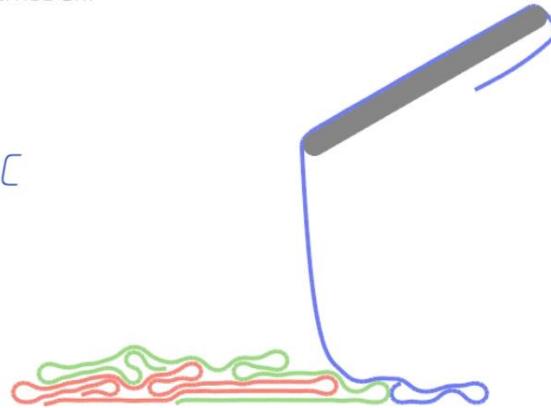
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Friction between fibers has been turned off.

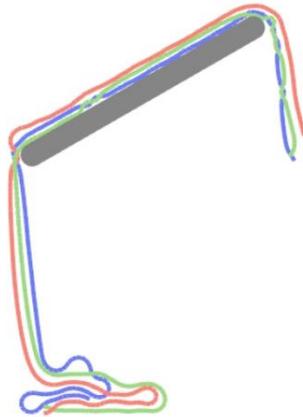
FLIP



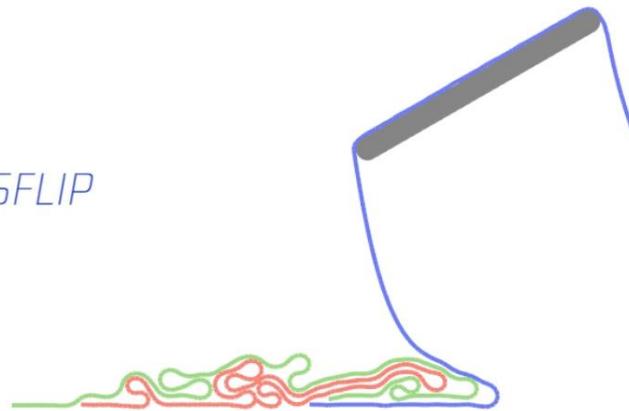
APIC

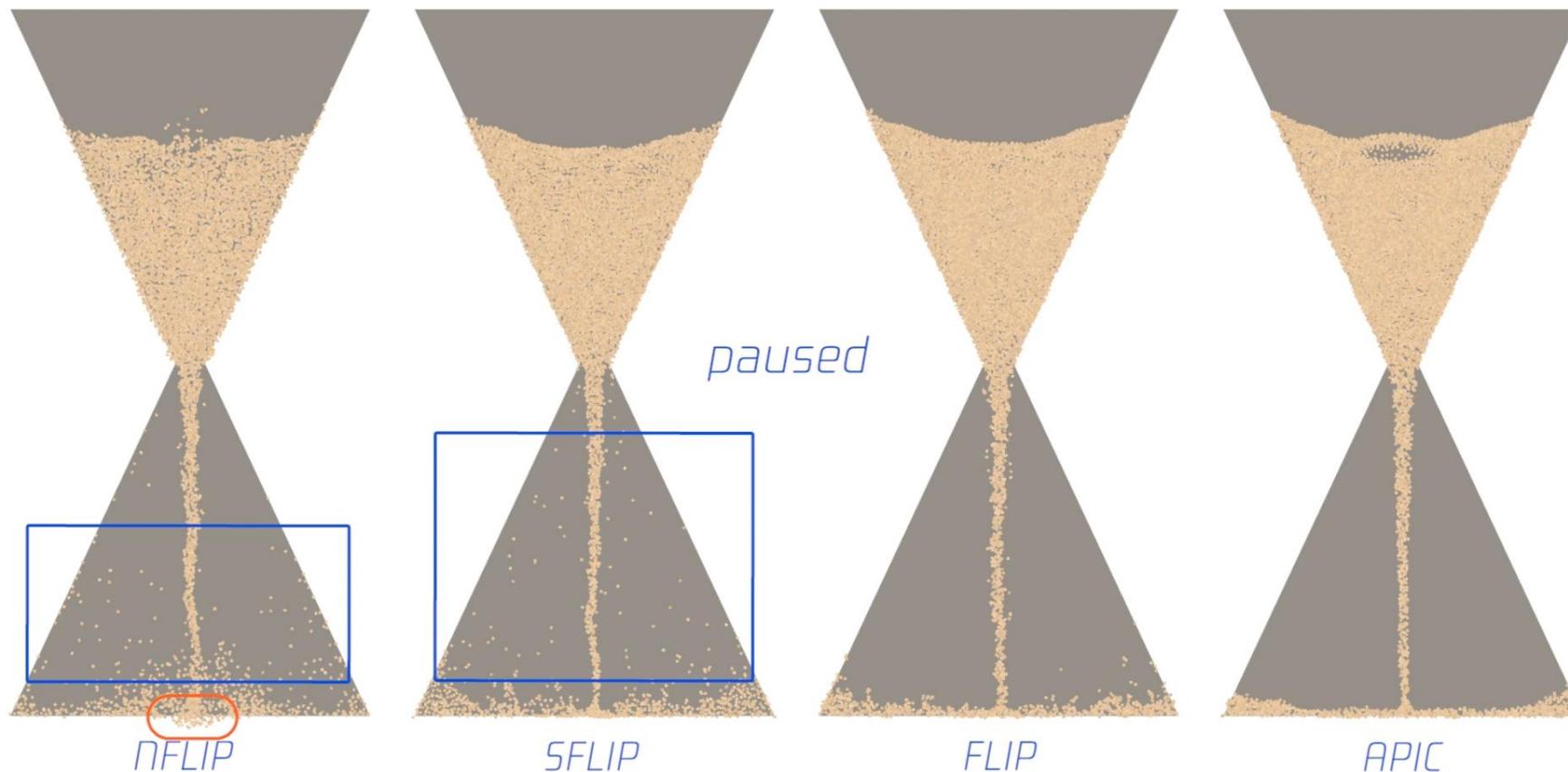


nFLIP



SFLIP







APIC



FLIP



APIC 2x resolution



FLIP 2x resolution



SFLIP



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**ASFLIP**

*AFFINE-AUGMENTED SEPARABLE FLIP*



Particle-to-grid transfer:

$$m_i^n \mathbf{v}_i^n = \sum_p w_{ip} m_p [\mathbf{v}_p^n + \mathbf{C}_p^n (\mathbf{x}_i^n - \mathbf{x}_p^n)]$$

APIC grid-to-particle transfer:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{C}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* (\mathbf{x}_i^n - \mathbf{x}_p^n)^T (\mathbf{D}_p^n)^{-1}$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

Add positional adjustment



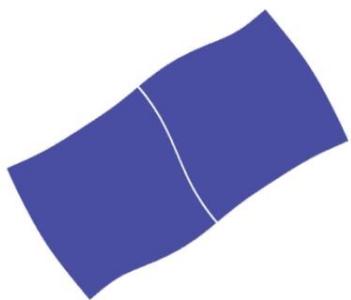
ASPIC grid-to-particle transfer:

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^*$$

$$\mathbf{C}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* (\mathbf{x}_i^n - \mathbf{x}_p^n)^T (\mathbf{D}_p^n)^{-1}$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \left[ \sum_i w_{ip} \mathbf{v}_i^* + \beta_p \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \right]$$

$$\beta_p = \begin{cases} 0, & \text{in boundary or source} \\ \beta_{\min}, & J_p < J_p^c \\ \beta_{\max}, & J_p \geq J_p^c \end{cases}$$



ASPIC doesn't work.

Assume zero force applied (i.e.,  $\mathbf{v}_i^* = \mathbf{v}_i^n$ ):

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip}^n \mathbf{v}_i^*$$

Root cause: PIC-style velocity update never preserves particle velocity from previous steps

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \left[ \sum_i w_{ip}^n \mathbf{v}_i^* + \beta_p \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip}^n \mathbf{v}_i^n \right) \right]$$



$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i \left[ (1 - \beta_p \alpha) w_{ip}^n \mathbf{v}_i^n + \beta_p \alpha w_{ip}^{n-1} \mathbf{v}_i^{n-1} \right]$$

Only depends on nodal velocity

Nodal velocity at  $t^n$

Nodal velocity at  $t^{n-1}$

AFLIP particle-to-grid transfer (P2G):

$$m_i^n \mathbf{v}_i^n = \sum_p w_{ip} m_p [\mathbf{v}_p^n + \mathbf{C}_p^n (\mathbf{x}_i^n - \mathbf{x}_p^n)] \longrightarrow \text{Preserves affine momentum during P2G}$$

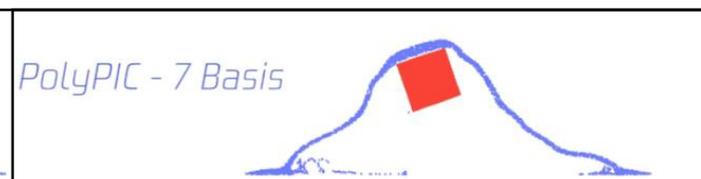
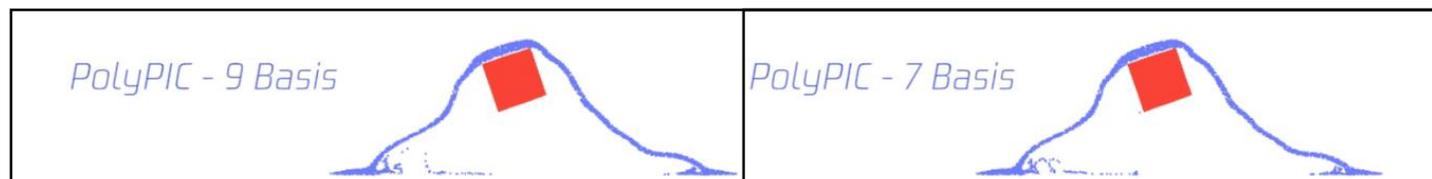
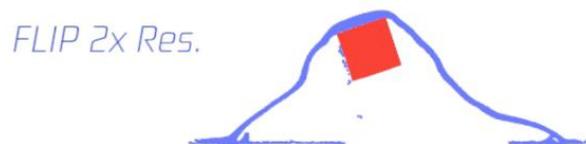
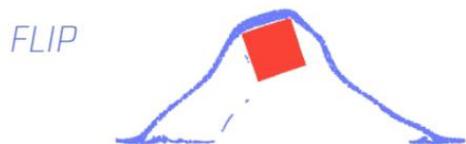
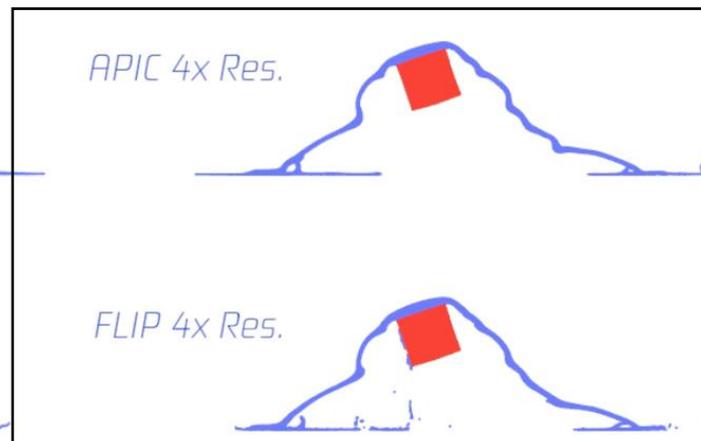
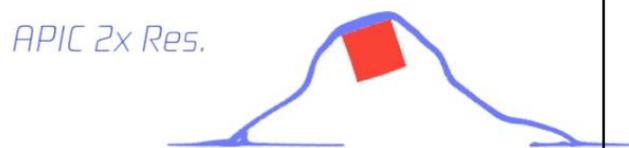
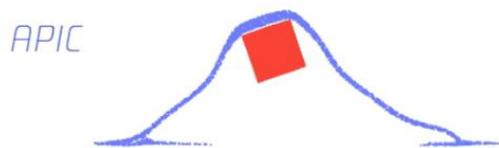
AFLIP grid-to-particle transfer (G2P):

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \longrightarrow \text{Preserves high-frequency momentum during G2P} \\ \text{(damped through } \alpha < 1 \text{)}$$

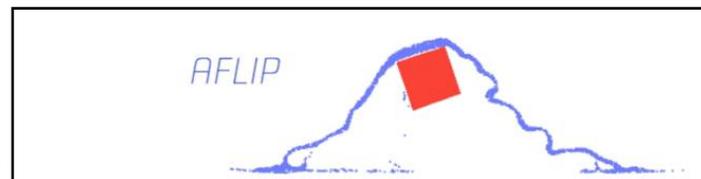
$$\mathbf{C}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* (\mathbf{x}_i^n - \mathbf{x}_p^n)^T (\mathbf{D}_p^n)^{-1}$$

$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \sum_i w_{ip} \mathbf{v}_i^*$$

# → 2D WEAKLY-COMPRESSIBLE LIQUID



paused





# ASFLIP

## AFFINE-AUGMENTED SEPARABLE FLUID-IMPLICIT PARTICLE



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ASFLIP particle-to-grid transfer (P2G):

$$m_i^n \mathbf{v}_i^n = \sum_p w_{ip} m_p [\mathbf{v}_p^n + \mathbf{C}_p^n (\mathbf{x}_i^n - \mathbf{x}_p^n)] \longrightarrow \text{Preserves affine momentum during P2G}$$

ASFLIP grid-to-particle transfer (G2P):

$$\mathbf{v}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* + \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \longrightarrow \text{Preserves high-frequency momentum during G2P} \\ \text{[damped through } \alpha < 1 \text{]}$$

$$\mathbf{C}_p^{n+1} = \sum_i w_{ip} \mathbf{v}_i^* (\mathbf{x}_i^n - \mathbf{x}_p^n)^T (\mathbf{D}_p^n)^{-1}$$

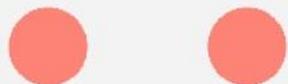
$$\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \left[ \sum_i w_{ip} \mathbf{v}_i^* + \beta_p \alpha \left( \mathbf{v}_p^n - \sum_i w_{ip} \mathbf{v}_i^n \right) \right] \longrightarrow \text{Improves upon cases where continuum assumption} \\ \text{no longer applies, preserving sub-grid movements}$$

$$\beta_p = \begin{cases} 0, & \text{in boundary or source} \\ \beta_{\min}, & J_p < J_p^c \\ \beta_{\max}, & J_p \geq J_p^c \end{cases}$$

PIC



APIC



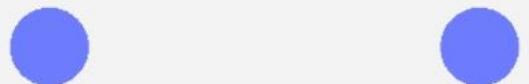
FLIP 0.99



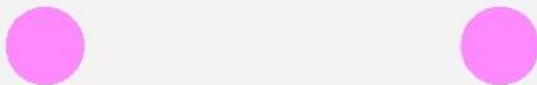
FLIP 0.995



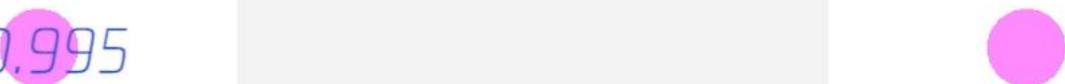
Full FLIP



nFLIP 0.99



nFLIP 0.995



ASFLIP 0.99



ASFLIP 0.995

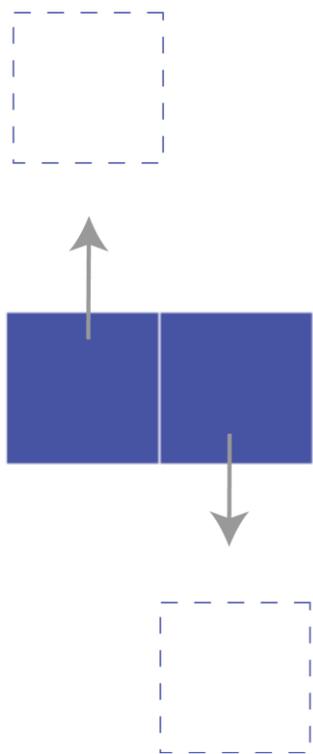


Ground Truth

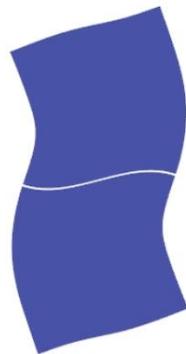


1.5Δx

Ground Truth



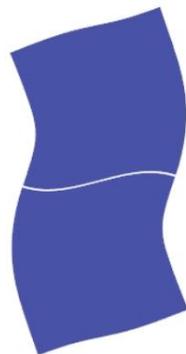
APIC



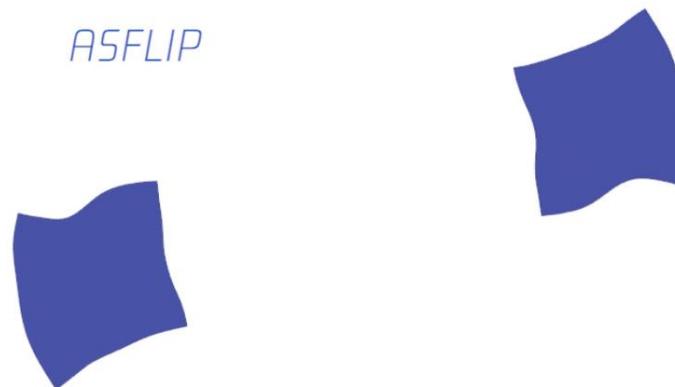
AFLIP



APIC +  
Positional  
Adjustment



ASFLIP





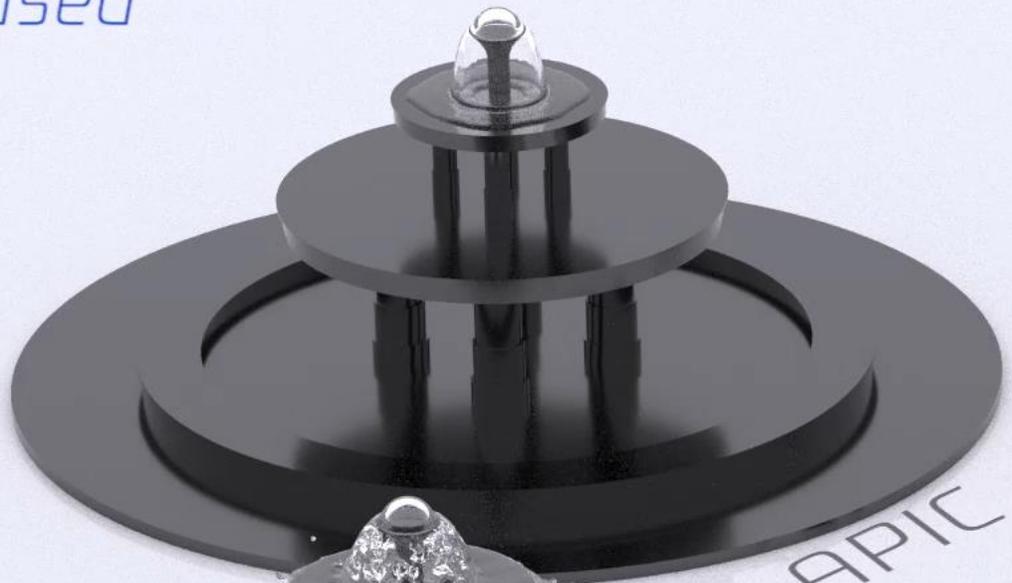
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***MORE EXAMPLES***

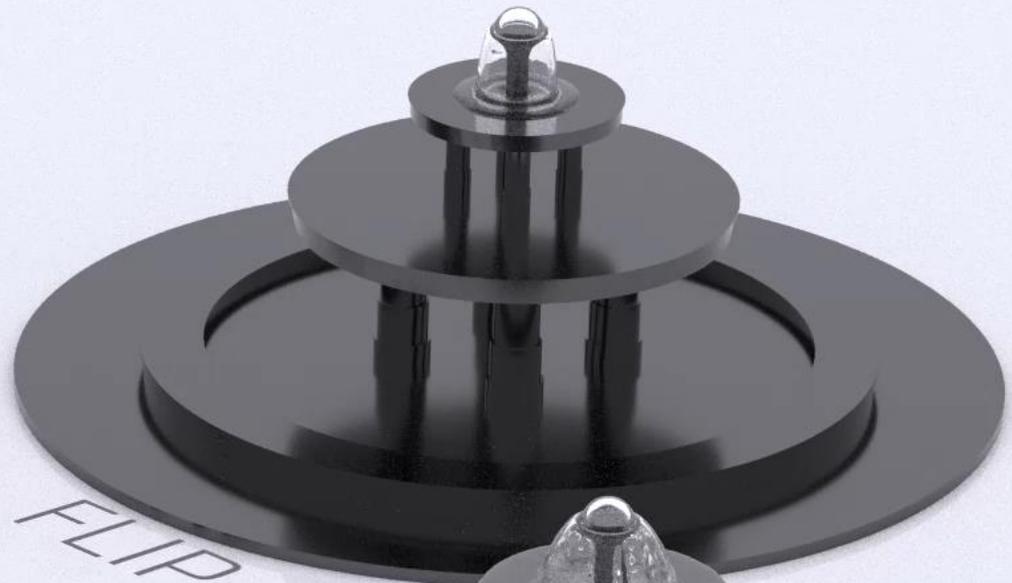
*WATER, SAND, HAIRS AND CLOTHES*



*paused*



APIC



FLIP



ASFLIP



AFLIP

APIC



ASFLIP



Paused

FLIP

nFLIP

SFLIP



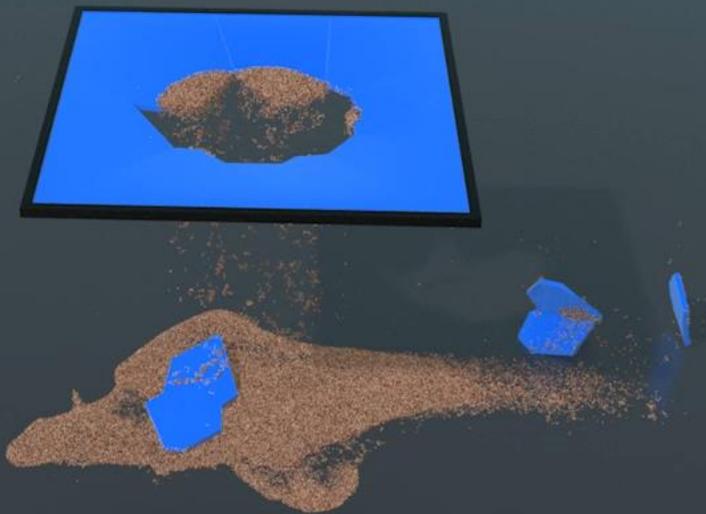
APIC

AFLIP

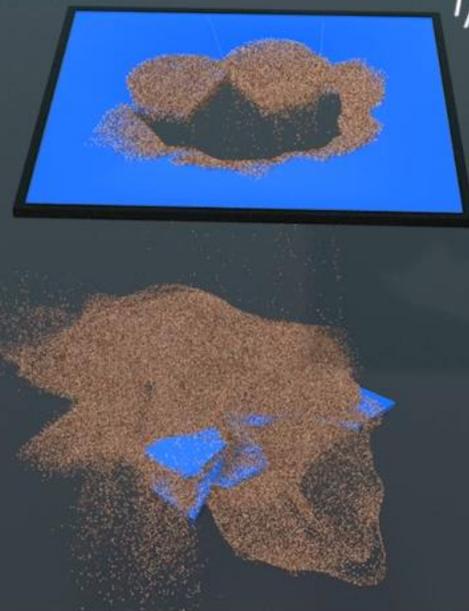
ASFLIP



FLIP

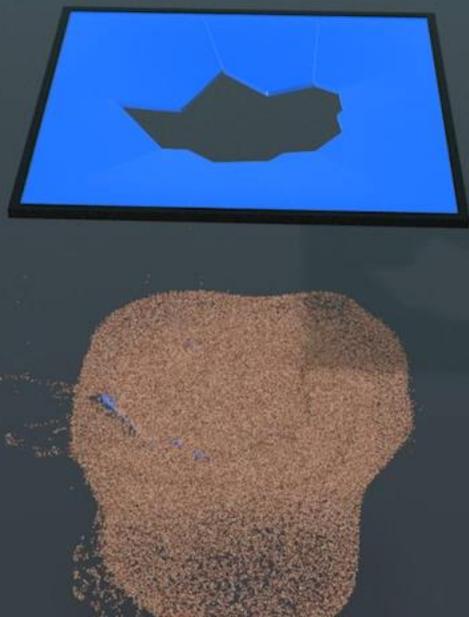


APIC



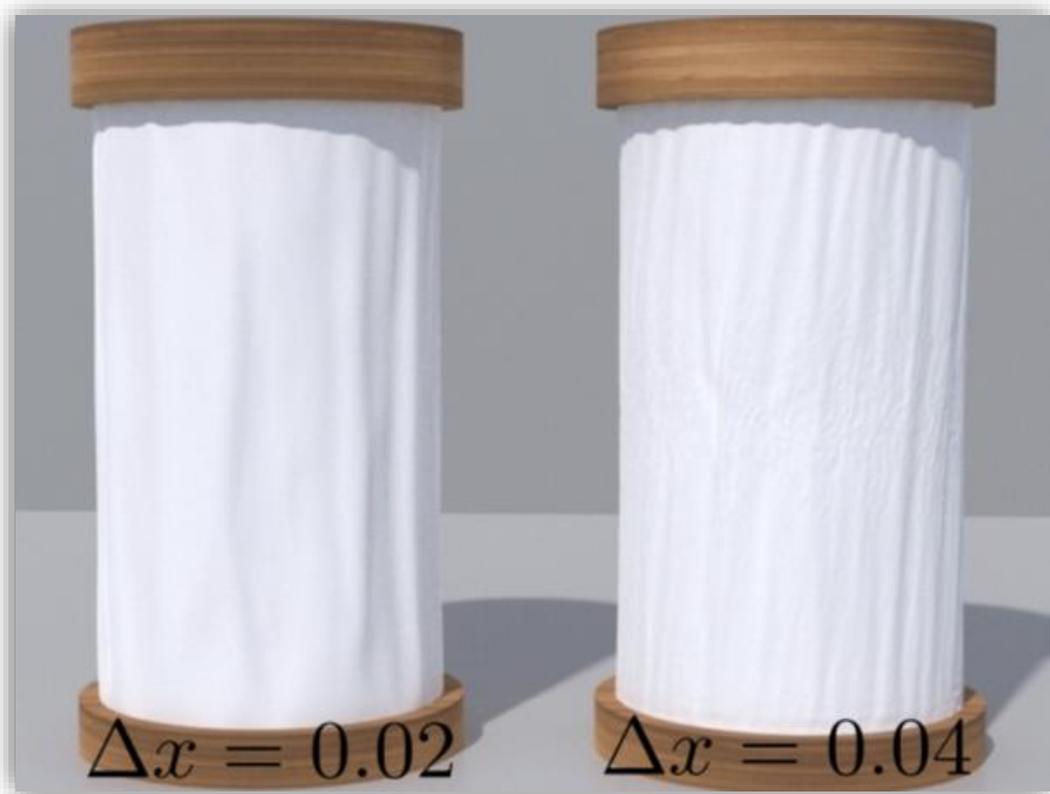
1/8x replay

SFLIP

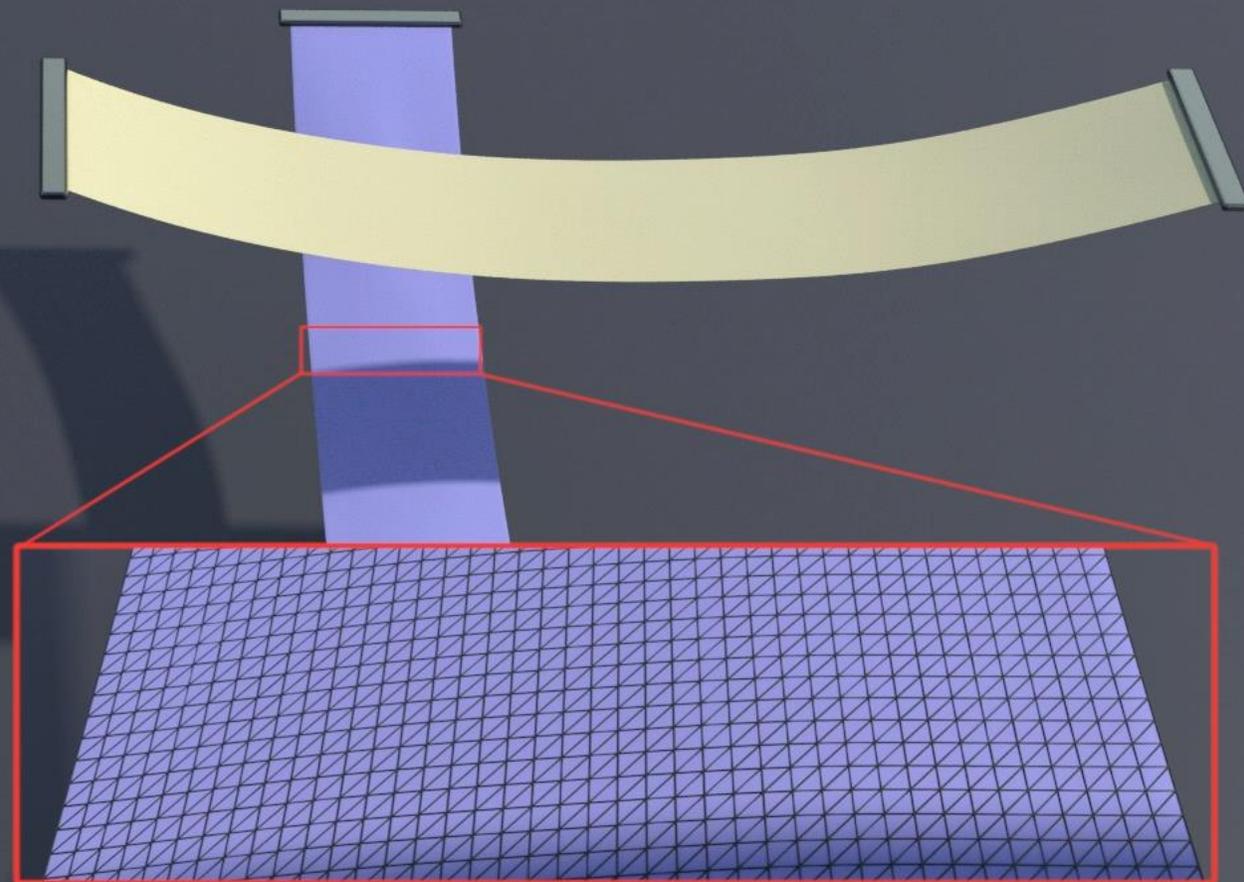


ASFLIP



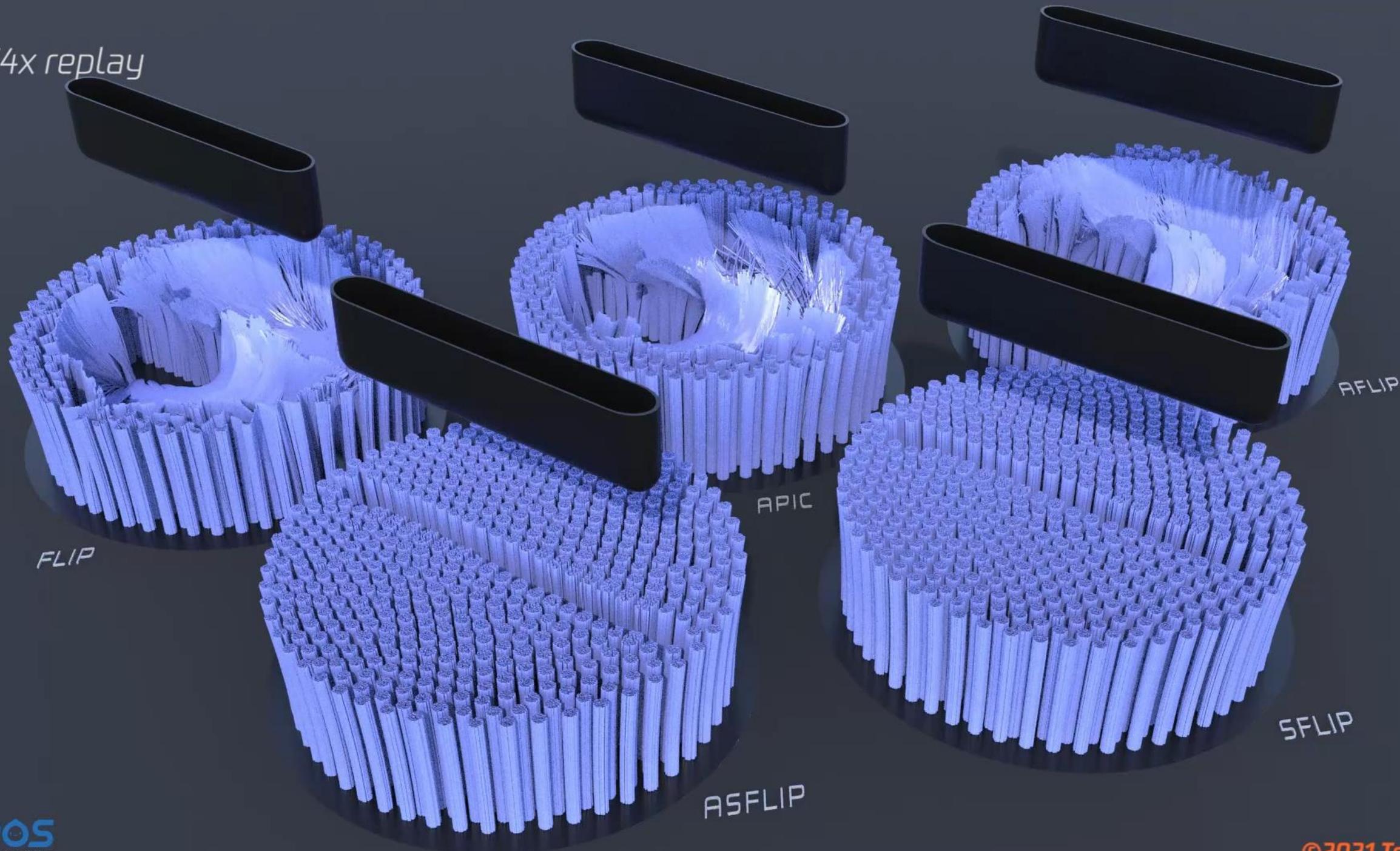


*Grid-resolution dependent wrinkling  
[Guo et al. 2018]*



ASFLIP

1/4x replay



FLIP

APIC

AFLIP

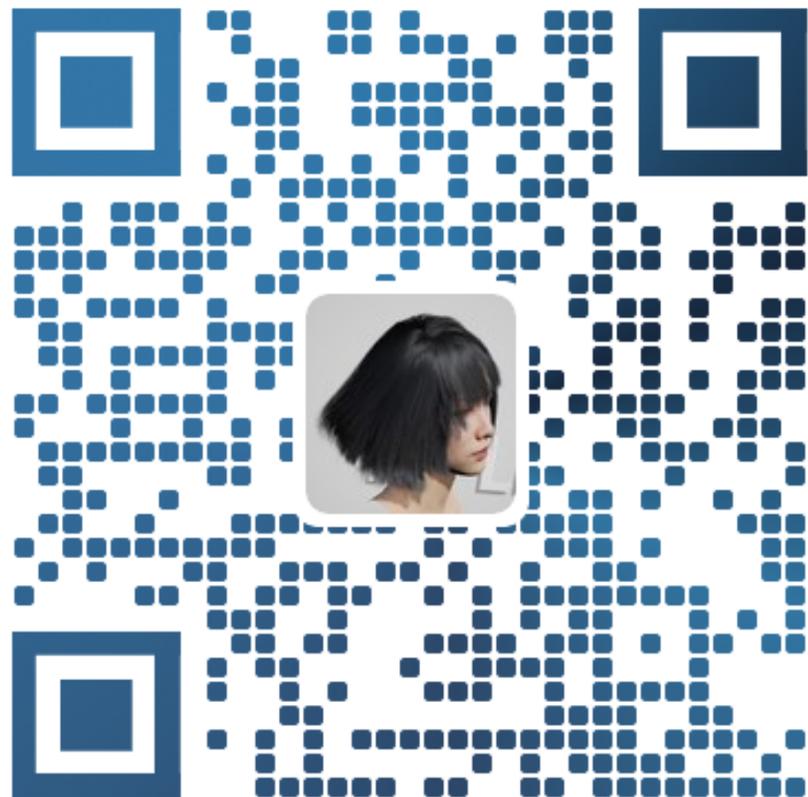
SFLIP

ASFLIP



<i>Integrators</i>	<i>High-frequency motion</i>	<i>Undamped affine motion</i>	<i>Handle Boundary Condition</i>	<i>Easy Separation</i>	<i>Energetic Level</i>
<i>PIC</i>	X	X	✓	X	★
<i>APIC</i>	X	✓	✓	X	★★
<i>FLIP</i>	✓	X	✓	X	★★
<i>nFLIP</i>	✓	X	X	X	★★
<i>SFLIP</i>	✓	X	✓	✓	★★
<i>AFLIP</i>	✓	✓	✓	X	★★★
<i>ASFLIP</i>	✓	✓	✓	✓	★★★★

- *Numerical volume gain*
- *Simulators based on Chorin's projection*
- *Determine separation through fracture mechanics*
- *More accurate (self-) contact resolution*
- *Coupling with principled, discrete physics*



*PRE-PRINT, VIDEO, SOURCE CODE*  
<http://yunfei.work/asflip/>

*TENCENT GAME AI RESEARCH CENTER*